

	Room 01 (101)	Room 02 (102)	Room 03 (103)	Room 04 (104)	Room 05 (105)	Room 06 (201)	Room 07 (202)	Room 08 (203)	Room 09 (204)
<b>October 14 (Wednesday)</b>									
09:10~10:40	<b>WA01(Special Session)</b> Korean Student Workshop: Do's and Don'ts in Paper Writing and Presentation	<b>WA02</b> [OS] SICE-ICROS Joint Organized Session on Control Theory and Application	<b>WA03</b> Adaptive Robust Control	<b>WA04</b> Service and Field Robots	<b>WA05</b> Automotive Systems and Automation	<b>WA06</b> Power Systems	<b>WA07</b> Neural Networks and Fuzzy Systems	<b>WA08</b> Navigation, Guidance and Control I	<b>WA09</b> Unmanned Aerial and Underwater Vehicles
11:00~12:00	Opening Ceremony & Plenary Lecture I (Room 205) - Karl Henrik Johansson, KTH Royal Institute of Technology : Cyber-secure Control Systems								
13:30~15:00	<b>WB01</b> [OS] Experimental Studies for Nonlinear Chemical Process Controls	<b>WB02</b> [OS] Recent Advances of Disturbance Observer and Applications to Motion Control	<b>WB03</b> New Control Approach	<b>WB04</b> Object/Human Visual Recognition	<b>WB05</b> Biomedical Systems	<b>WB06</b> Sensor Fusion and Signal Processing	<b>WB07</b> Communication and Embedded Systems	<b>WB08</b> [OS] Navigation, Guidance, and Control II	<b>WB09</b> [OS] Autonomy of Unmanned Marine Vehicles
15:20~16:20	Plenary Lecture II (Room 205) - Peng Shi, University of Adelaide : Analysis and Design on Dynamical Systems with Hybrid Structure								
16:30~18:00	<b>WC01(Special Session)</b> Advances in Underwater Vehicle	<b>WC02</b> [OS] Vehicle Control	<b>WC03</b> Sliding Mode Control	<b>WC04</b> Mobile Robots and Navigation	<b>WC05</b> Information and Networking	<b>WC06</b> Process Systems and Data Fusion	<b>WC07</b> [OS] Statistical Inference and Data Mining	<b>WC08</b> [OS] Navigation and Control Application for Military Robot Systems	<b>WC09</b> Unmanned Ground Vehicles
<b>October 15 (Thursday)</b>									
09:10~10:40	<b>TA01</b> [OS] Control Techniques for Mechanical systems	<b>TA02</b> [OS] Sensing and Control System Application for Marine Systems	<b>TA03</b> Robot Mechanism and Control	<b>TA04</b> Biorobotics and Medical Robots	<b>TA05</b> [OS] Electro-Hydraulic System	<b>TP (Room 201&amp;202&amp;203&amp;204)</b>			
11:00~12:00	Plenary Lecture III (Room 205) - Jay A. Farrell, University of California, Riverside : Precision Mapping and Vehicle State Estimation for Autonomous Highway Vehicles					<b>Interactive Poster Session I</b> (17:00~18:30)  - Control Theory and Applications - Robotics - Signals and Intelligent Systems			
13:00~14:30	<b>TB01(Special Session)</b> How to Achieve Successful Technology Transfer	<b>TB02</b> [OS] SICE-ICROS Joint Organized Session on Intelligent Robot System	<b>TB03</b> Nonlinear Systems	<b>TB04</b> [OS] Machine Vision Applications	<b>TB05</b> [OS] Image based Ambient Intelligence				
14:50~16:50	Plenary Lecture IV (Room 205) - Yoshihiko Nakamura, University of Tokyo : Disaster-Response Humanoid Robots: Focusing on Actuators and Power Source for Field Robots Plenary Lecture V (Room 205) - Sangbae Kim, Massachusetts Institute of Technology : The MIT Cheetah: New Design Paradigm for Mobile Robots								
<b>October 16 (Friday)</b>									
09:10~10:40	<b>FA01(Special Session)</b> Bio-inspired Robot Design	<b>FA02</b> Control Applications I	<b>FA03</b> [OS] Time Delay and Their Applications	<b>FA04</b> [OS] Medical Robotics and Simulation	<b>FA05</b> [OS] Health Care Technology	<b>FA06 (Room206)</b> [OS] Signal and Image Processing	<b>FP (Room 201&amp;202&amp;203&amp;204)</b>		
11:00~12:00	Plenary Lecture VI (Room 205) - David Boas, Harvard Medical School : Functional Near Infrared Spectroscopy – What is it and its potential role in brain-computer interfacing?					<b>Interactive Poster Session II</b> (16:30~18:00)  - Autonomous Vehicles - Bio-Systems - Industrial Applications			
13:30~15:00	<b>FB01(Special Session)</b> fNIRS Forum : Toward a Mobile Brain Imager (13:30~15:50)	<b>FB02</b> Control Applications II	<b>FB03</b> Identification and Estimation	<b>FB04</b> Human-Robot Interaction and Visual Servoing	<b>FB05</b> Civil and Urban Systems				
15:20~16:20	Plenary Lecture VII (Room 205) - Taek Lyul Song, Hanyang University : Computationally Efficient Multi-target Data Association								